Recognizing Interactions: A First-Person Perspective

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Motivation

- Humans interact with their surrounding environment at every moment in their lives.
- A common type of interaction consists of tasks which involve manipulation and movement of objects.
- Another popular kind of interaction involves social activities.
- Our goal is to detect these behaviors in day-long videos of individuals using a wearable camera system.



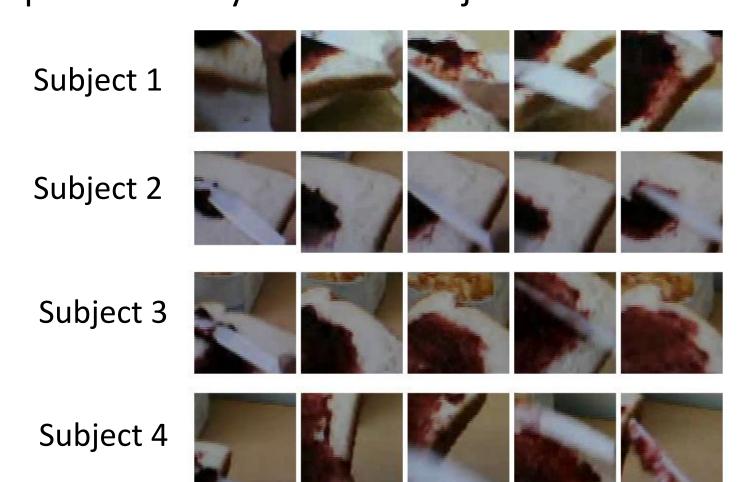


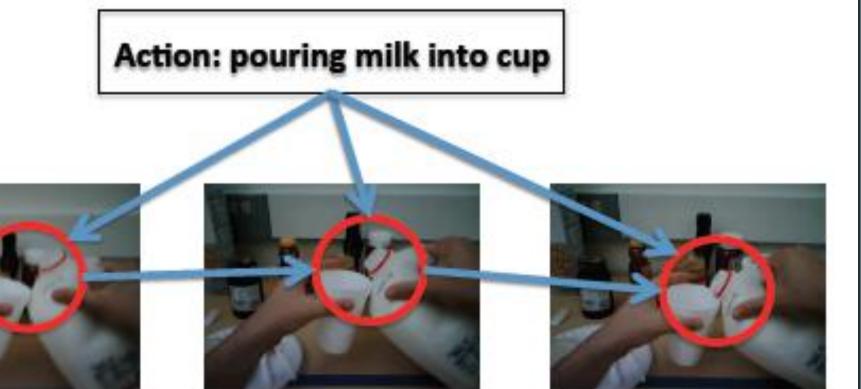




Object-Manipulation Tasks

- A small window of pixels extracted from around gaze is:
- (1) very informative on what the action is
- (2) appears consistently similar among different instances of the same action performed by different subjects





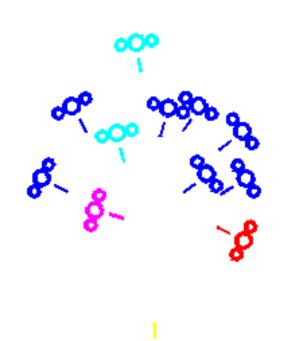
We use three sets of features for each pixel location in image: Object-based features, Appearance Features, and future manipulation features.



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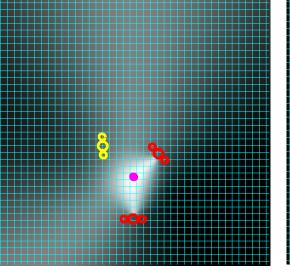
Social Interactions

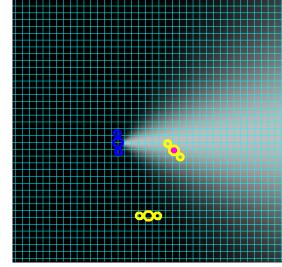




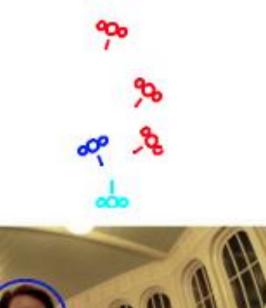
- Face location in image → Angle from first-person view
- Face size in image → Distance from first-person

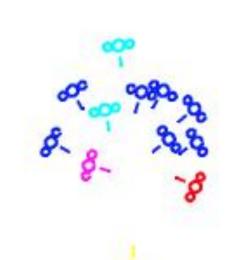




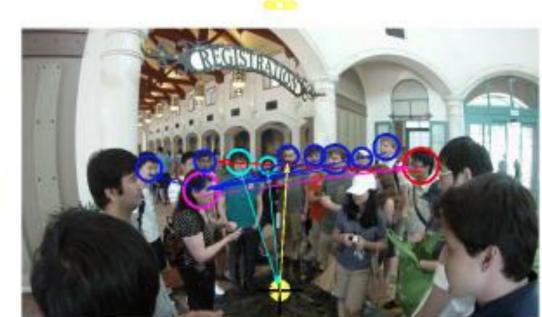


- We discretize the space into a grid.
- Our goal is to estimate at which grid point each face is looking.
- People more likely look at where their head is oriented to.
- People more likely look at faces rather than random locations.
- People more likely look at what others are looking at.

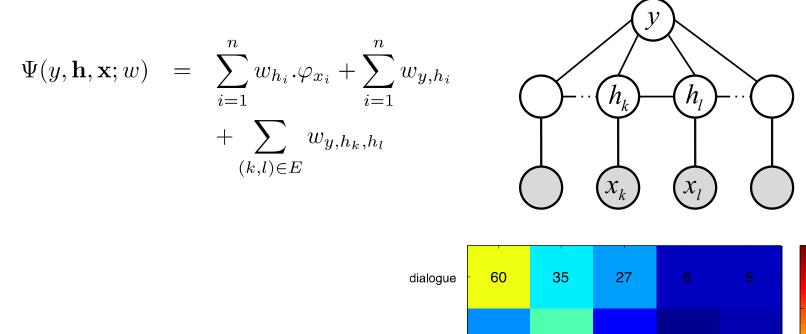




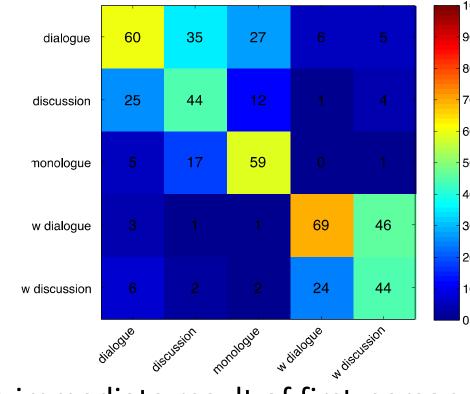




- Roles are assigned to an individual (x) based on the following four features:
 - Number of faces looking at x
 - Whether first-person looks at *x*
 - If there is mutual attention between first-person and *x*
 - Number of faces looking at where x is attending
- We learn a HCRF on top of attention, location and head-motion features.



 Confusion matrix for recognizing different types of social interaction.



- We can build a social network as an immediate result of first-person vision
- Our algorithm simply counts the number of times each face cluster appears in a subject's video

